



Convex Minimization in \mathbb{R}^n

Uwe Naumann



Informatik 12: Software and Tools for Computational Engineering (STCE) RWTH Aachen University

Contents





Objective and Learning Outcomes

Least-Squares Objective

Optimality Conditions

Linear Model

Optimality Conditions Implementation

Nonlinear Model

Optimality Conditions Implementation





Objective and Learning Outcomes

Least-Squares Objective

Optimality Conditions

Linear Mode

Optimality Conditions Implementation

Nonlinear Mode

Optimality Conditions Implementation

Objective and Learning Outcomes





Objective

► Introduction to sample code approaching the Modern Family example as a general convex minimization problem.

Learning Outcomes

- You will understand
 - the formulation of the Modern Family example as a general convex minimization problem
 - its solution using the general-purpose optimization methods steepest descent and Newton's method.
- You will be able to
 - run the sample code
 - compare the results





Objective and Learning Outcomes

Least-Squares Objective

Optimality Conditions

Linear Mode

Optimality Conditions Implementation

Nonlinear Mode

Optimality Conditions Implementation



We state the Modern Family example for model

$$y = f(\mathbf{p}, \mathbf{x}) : \mathbf{R}^n \times \mathbf{R}^n \to \mathbf{R}$$

as minimization of the error function

$$E(\mathbf{p}, X, \mathbf{y}) = \sum_{i=0}^{m-1} (f(\mathbf{p}, \mathbf{x}_i^T) - y_i)^2$$

Linear (in p)

$$y = \mathbf{p}^T \cdot \mathbf{x}$$

and nonlinear

$$y = (\mathbf{p}^T \cdot \mathbf{x})^2$$

models are considered.





Objective and Learning Outcomes

Least-Squares Objective

Optimality Conditions

Linear Mode

Optimality Conditions Implementation

Nonlinear Mode

Optimality Conditions Implementation



Necessary

Optimality Conditions

$$\frac{dE}{d\mathbf{p}}(\mathbf{p}, X, \mathbf{y}) = 2 \cdot \sum_{i=0}^{m-1} \left((f(\mathbf{p}, \mathbf{x}_i^T) - y_i) \cdot \frac{df}{d\mathbf{p}}(\mathbf{p}, \mathbf{x}_i^T) \right) \rightarrow \mathbf{0}$$

Sufficient

$$\mathbf{v}^T \cdot \frac{d^2 E}{d\mathbf{p}^2}(\mathbf{p}, X, \mathbf{y}) \cdot \mathbf{v} > 0 \quad \forall \mathbf{v} \neq \mathbf{0} \in \mathbf{R}^n$$

where

$$\frac{d^2 E}{d\mathbf{p}^2} = 2 \cdot \sum_{i=0}^{m-1} \left(\frac{df}{d\mathbf{p}} (\mathbf{p}, \mathbf{x}_i^T)^T \cdot \frac{df}{d\mathbf{p}} (\mathbf{p}, \mathbf{x}_i^T) + \frac{d^2 f}{d\mathbf{p}^2} (\mathbf{p}, \mathbf{x}_i^T) \cdot (f(\mathbf{p}, \mathbf{x}_i^T) - y_i) \right)$$





Objective and Learning Outcomes

Least-Squares Objective

Optimality Conditions

Linear Model

Optimality Conditions Implementation

Nonlinear Model

Optimality Conditions Implementation

Optimality Conditions for Linear Model



For
$$y = f(\mathbf{p}, \mathbf{x}) = \mathbf{p}^T \cdot \mathbf{x} = \mathbf{x}^T \cdot \mathbf{p}$$

$$E(\mathbf{p}, X, \mathbf{y}) = \sum_{i=0}^{m-1} (f(\mathbf{p}, \mathbf{x}_i^T) - y_i)^2 = \sum_{i=0}^{m-1} (\mathbf{x}_i \cdot \mathbf{p} - y_i)^2$$

and hence

$$\frac{dE}{d\mathbf{p}}(\mathbf{p}, X, \mathbf{y}) = 2 \cdot \sum_{i=0}^{m-1} (\mathbf{x}_i \cdot \mathbf{p} - y_i) \cdot \mathbf{x}_i \in \mathbb{R}^{1 \times n}$$

and

$$\frac{d^2 E}{d\mathbf{p}^2}(\mathbf{p}, X, \mathbf{y}) = 2 \cdot \sum_{i=0}^{m-1} \mathbf{x}_i^T \cdot \mathbf{x}_i \in \mathbf{R}^{n \times n}.$$



We present implementations for the solution of the convex unconstrained minimization problem

$$\min_{\mathbf{p}\in R^n} E(\mathbf{p},X,\mathbf{y})$$

using

- steepest descent
- Newton's method.

See source code.





Objective and Learning Outcomes

Least-Squares Objective

Optimality Conditions

Linear Mode

Optimality Conditions Implementation

Nonlinear Model

Optimality Conditions Implementation

Optimality Conditions for Nonlinear Model



For
$$y = f(\mathbf{p}, \mathbf{x}) = (\mathbf{p}^T \cdot \mathbf{x})^2 = (\mathbf{x}^T \cdot \mathbf{p})^2$$

$$E(\mathbf{p}, X, \mathbf{y}) = \sum_{i=0}^{m-1} (f(\mathbf{p}, \mathbf{x}_i^T) - y_i)^2 = \sum_{i=0}^{m-1} (\mathbf{x}_i \cdot \mathbf{p} - y_i)^2$$

and hence

$$\frac{dE}{d\mathbf{p}}(\mathbf{p}, X, \mathbf{y}) = 4 \cdot \sum_{i=0}^{m-1} ((\mathbf{x}_i \cdot \mathbf{p})^3 - y_i \cdot \mathbf{x}_i \cdot \mathbf{p}) \cdot \mathbf{x}_i$$

and

$$\frac{d^2 E}{d\mathbf{p}^2}(\mathbf{p}, X, \mathbf{y}) = 4 \cdot \sum_{i=0}^{m-1} (3 \cdot (\mathbf{x}_i \cdot \mathbf{p})^2 - y_i) \cdot \mathbf{x}_i^T \cdot \mathbf{x}_i.$$

Calibration of Linear Model





We present implementations for the solution of the convex unconstrained minimization problem

$$\min_{\mathbf{p}\in R^n} E(\mathbf{p}, X, \mathbf{y})$$

using

- steepest descent
- Newton's method with differentiation performed
 - symbolically
 - approximately (finite differences)
 - ▶ algorithmically (dco/c++)

See source code.





Objective and Learning Outcomes

Least-Squares Objective

Optimality Conditions

Linear Mode

Optimality Conditions Implementation

Nonlinear Mode

Optimality Conditions Implementation

Summary and Next Steps





Summary

- ► Introduction to sample code approaching the Modern Family example as a general convex minimization problem.
- Solution of Modern Family problem using steepest descent and Newton's method.

Next Steps

- ► Run the sample code.
- Compare the results.
- Continue the course to find out more ...